

Basic Teaching Unit for the Study of Regulation and Control RYC/B



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DESCRIPTION =

RYC/B allows the user to learn the basics about regulation and control of first and second order systems.

This unit enables to carry a set of practices related with basic regulation and control, through which the user will understand how to characterize first and second order systems and how a PID controller works.

The unit has three modules: reference signals, PID Controller, first order system and second order system module.

SPECIFICATIONS -

Systems:

Manuals:

First Order System:

Second Order System:

Time constant T : 1ms to 100 ms

Damping coefficient ξ : 0 to 1.5.

Cables and Accessories, for normal operation.

Maintenance & Practices Manuals.

Natural frequency (ω_n): 2* π *100 rad/s (100Hz)

This unit is supplied with the following manuals: Required

Services, Assembly and Installation, Starting-up, Safety,

Metallic enclosure, including all the modules and elements.

Power Supply.

Protection fuse.

Block diagrams in the front panel.

Modules:

Reference signals:

Step:Amplitude: ± 10 V. Frequency: 0Hz to 1000Hz.Ramp:Amplitude: ± 10 V. Frequency: 0Hz to 1000Hz.Sine:Amplitude: ± 10 V. Frequency: 0Hz to 1000Hz.

PID controller:

P controller: Kp: 0 to 10. I controller: Ti: 1 ms to 10 ms. D controller: Td: 1 ms to 10 ms.



ISO 9000: Quality Management (for Design, Manufacturing, Commercialization and After-sales service)



European Union Certificate (total safety)

Certificates ISO 14000 and ECO-Management and Audit Scheme (environmental management)



Worlddidac Quality Charter Certificate (Worlddidac Member)

Response of a first order system in time domain



Step-Response Time Constant=10ms



Ramp-Response Time Constant=10ms



Sinusoidal-Response T=10ms

Response of a second order system in time domain



Step-Response Damping Coefficient $\xi{=}0.5$



Ramp-Response Damping Coefficient $\xi{=}0.5$



Sinusoidal-Response Damping Coefficient ξ =0.5

Some typical exercises results screens (continuation)



Response of a second order system in time domain (continuation)

Step-Response Damping Coefficient $\xi{=}0.2$



Ramp-Response Damping Coefficient $\xi{=}0.2$



Sinusoidal-Response Damping Coefficient ξ =0.2

Some typical exercises results screens (continuation)



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Some typical exercises results screens (continuation)



EXERCISES AND PRACTICAL POSSIBILITIES

Some Practical Possibilities of the Unit:

- 1.- Response of a first order system in time domain. (Step-response).
- 2.- Response of a first order system in time domain. (Rampresponse).
- 3.- Response of a first order system in time domain. (Sinusoidal-response).
- 4.- Response of a first order system in frequency domain (Sinusoidal-response).
- 5.- Response of a second order system in time domain (Stepresponse).
- 6.- Response of a second order system in time domain. (Rampresponse).
- 7.- Response of a second order system in time domain. (Sinusoidal-response).
- 8.- Response of a second order system in frequency domain (Sinusoidal-response).
- 9.- Structure of a PID controller (Proportional-Integrative-Derivative blocks).
- 10.-PID control of a first order system in open-loop.
- 11.-PID control of a second order system in open-loop.
- 12.- PID control of a first order system in closed- loop. (Mathematical tuning).
- 13.-PID control of a first order system in closed- loop. (Experimental tuning)
- 14.-PID control of a first order system in closed- loop. (Ziegler Nichols tuning).
- 15.-PID control of a second order system in closed- loop. (Mathematical tuning).

REQUIRED SERVICES =

- Electrical supply: single-phase, 220V./50Hz or 110V./60Hz.

- 16.-PID control of a second order system in closed- loop. (Experimental tuning).
- 17.-PID control of a second order system in closed- loop. (Ziegler Nichols tuning).

DIMENSIONS & WEIGHTS =

- Dimensions: 490 x 330 x 310 mm. approx.
- Weight: 10 Kg. approx.

OPTIONAL AND ADDITIONAL

EDAS/VIS. EDIBON Data Acquisition System/Virtual Instrumentation System.

 $\label{eq:CAL} CAL \mbox{ CAL } {\rm Computer} \mbox{ Aided } {\rm Instruction} \mbox{ Software } {\rm System}.$

 ${\sf CAL}.\ {\rm Computer}\ {\rm Aided}\ {\rm Learning}\ {\rm Software}\ ({\rm Results}\ {\rm Calculation}\ {\rm and}\ {\rm Analysis}).$



* Software available in English and Spanish. Any other language available on request.

CAI. Computer Aided Instruction Software System



With no physical connection between unit and computer, this complete package consists on an Instructor Software (INS/ SOF) totally integrated with the Student Software (RYC/B/SOF). Both are interconnected so that the teacher knows at any moment what is the theoretical and practical knowledge of the students. These, on the other hand, get a virtual instructor who helps them to deal with all the information on the subject of study.

Examples of the Software screens

With the INS/SOF. Classroom Management Software Package (Instructor Software), the Instructor has a whole range of options, among them:

- Organize Students by Classes and Groups.
- Create easily new entries or delete them.
- Create data bases with student information.
- Analyze results and make statistical comparisons.
- Print reports.
- Develop own examinations.
- Detect student's progress and difficulties.
- ...and many other facilities.

This Instructor Software, working in network configuration, allows controlling all the students in the classroom.

RYC/B/SOF. Computer Aided Instruction Software Package (Student Software).

It explains how to use the unit, run the experiments and what to do at any moment.

- The options are presented by pulldown menus and pop-up windows.
- Each Software Package contains:

Theory: that gives the student the theoretical background for a total understanding of the studied subject.

Exercises: divided by thematic areas and chapters to check out that the theory has been understood.

Guided Practices: presents several practices to be done, alongside the unit, showing how to complete exercises and practices.

Exams: set of questions presented to test the obtained knowledge.





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CAL. Computer Aided Learning Software (Results Calculation and Analysis)

This Computer Aided Learning Software (CAL) is a Windows based software, simple and very easy to use specifically developed by EDIBON. It has been designed to cover different areas of science: Basic Electronics, Communications, Basic Electricity, Energy, Mechanics, Basic Fluid Mechanics and General Fluid Mechanics*. *Although only the purchased areas will be activated and ready to use.

CAL is a class assistant that helps in making the necessary calculations to extract the right conclusions from data obtained during the experimental practices. With a single click, CAL computes the value of all the variables involved. Also, CAL gives the option of plotting and printing the results.





Once the Area of study is selected, the right module can be chosen among a wide range, each one with its own set of lab exercises.



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Among the given choices, an additional help button can be found, which offers a wide range of information, such as constant values, unit conversion factors and integral and derivative tables.

Quantity	Symbol	Value
characteristic impedance of vacuum	$Z_n = \mu_0 c$	376 730 313 461_ Ω
electric constant (permittivity of free space)	$\epsilon_0 = 1/(\mu_3 c^2)$	8 854 187 817
magnetic constant (permeability of free space)	<i>P</i> +	$\begin{array}{l} 4\alpha \times 10^{17} N A^{12} - \\ 1 2566 370 614 \\ 10^{16} N A^{12} \end{array}$
Newtonian constant of gravitation	G	$6.6742(10) \approx 10^{2}$ $11_{m^{3}kg} (1_{s})^{2}$
Planck's constant	A	5.626.0693(11) × 10 ⁻³⁴ Js
Dirac's constant	$\hbar = h/(2\pi)$	1.054 571 68(18)

It provides a handy option to avoid using atterent reference sources while in progress. For example: the values of Physical constants, their symbols and right names, conversion factors...



...and the very useful Integral and Derivative tables.

REPRESENTATIVE:

* Software is available in English and Spanish. Any other language available on request.

*Specifications subject to change without previous notice, due to the convenience of improvements of the product.



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