

- Totally safe, utilizing 4 safety systems (Mechanical, Electrical, Electronic & Software).
- Designed and manufactured under several quality standards.
- Optional CAL software helps the user perform calculations and comprehend the results.
- \blacktriangleright This unit has been designed for future expansion and integration. A common expansion is the EDIBON Scada-Net (ESN) System which enables multiple students to simultaneously operate many units in a network.

For more information about Key Features, click here:











ISO 9000: Quality Management (for Design, Manufacturing, Commercialization and After-sales service)

(total safety)

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Certificates ISO 14000 and ECO-Management and Audit Scheme (environmental management)

Common items for all Process Control parameters

1 UCPCV-UB. Base Unit:

Bench-top unit.

This unit is common for all Sets for Process Control type "UCPCV" and can work with one or several sets.

Anodized aluminium structure and panels in painted steel.

Main metallic elements in stainless steel.

Diagram in the front panel with similar distribution to the elements in the real unit.

A transparent main tank and collector with an orifice in the central dividing wall ($2x25 dm^3$), and drainage in both compartments.

A transparent dual process tank (2x10 dm³), interconnected through an orifice and a ball valve and an overflow in the dividing wall; a graduate scale and a threaded drain of adjustable level with bypass.

2 Centrifugal pumps, range: 0-10 l./min.

2 Variable area flow meters (0.2-2 I./min, and 0.2-10 I./min), and with a manual valve. Line of on/off regulation valves (solenoid). Usually one is normally opened, and the other two are normally closed, and manual drainage valves of the upper tank.

Speed controller of the centrifugal pump AB-1 (located into the Control Interface Box). Range: 0-50 Hz .

Any Set for Process Control type "UCPCV" will be supplied installed in the Base Unit and ready for working.

②UCPCV/CIB. Control Interface Box :

This unit is common for all Sets for Process Control type "UCPCV" and can work with one or several sets.

Control interface box with process diagram in the front panel and with the same distribution that the different elements located in the unit, for an easy understanding by the student.

All sensors, with their respective signals, are properly manipulated from -10V. to +10V computer output. Sensors connectors in the interface have different pines numbers (from 2 to 16), to avoid connection errors. Single cable between the control interface box and computer.

The unit control elements are permanently computer controlled, without necessity of changes or connections during the whole process test procedure. Simultaneous visualization in the computer of all parameters involved int the process. Calibration of all sensors involved in the process.

Real time curves representation about system responses. Storage of all the process data and results in a file. Graphic representation, in real time, of all the process/system responses.

All the actuators' values can be changed at any time from the keyboard allowing the analysis about curves and responses of the whole process. All the actuators and sensors values and their responses are displayed on only one screen in the computer.

Shield and filtered signals to avoid external interferences.

Real time PID control with flexibility of modifications from the computer keyboard of the PID parameters, at any moment during the process. Real time PID and on/off control for pumps, compressors, resistances, control valves, etc. Real time PID control for parameters involved in the process simultaneously.

Open control allowing modifications, at any moment and in real time , of parameters involved in the process simultaneously.

Proportional control, integral control and derivative control, based on the real PID mathematical formula, by changing the values, at any time, of the three control constants (proportional, integral and derivative constants).

Possibility of automatization of the actuators involved in the process.

Three safety levels, one mechanical in the unit, other electronic in the control interface and the third one in the control software.

③DAB. Data Acquisition Board:

This board is common for all Sets for Process Control type "UCPCV".

PCI Data acquisition board (National Instruments) to be placed in a computer slot. Bus PCI. Analog input:

Number of **channels = 16** single-ended or 8 differential. **Resolution = 16 bits**, 1 in 65536.

Sampling rate up to: 250 KS/s (Kilo samples per second). Input range (V) = ± 10 V.

 ${\sf Data\ transfers=DMA, interrupts, programmed\ I/0.\ Number\ of\ DMA\ channels=6.}$

Analog output:

Number of **channels=2**. **Resolution=16 bits**, 1 in 65536.

Maximum output rate up to: 833 KS/s.

 $Output range(V) = \pm 1 \text{ OV}. Data transfers = DMA, interrupts, programmed I/0.$

Digital Input/Output:

Number of **channels=24 inputs/outputs**. D0 or DI Sample Clock frequency: 0 to 1 MHz.

Timing: Counter/timers=2. Resolution: Counter/timers: 32 bits.



UCPCV-UB



UCPCV/CIB



(4) Sets (sensor and elements + computer control software) used in the base unit: UCPCV-T. Set for Temperature Process Control: This Set will be supplied and installed in the Base Unit and ready for working. a) Sensor and elements: Temperature sensor "J type". Electric resistor (0.5 KW), with thermostat (70 °C). Helix agitator, range: 0-300 r.p.m. On/off level switch; safety element that permits the resistance to operate just when the level of water is sufficient. b) Computer Control Software: Computer Control + Data Acquisition + Data Management Software for Temperature Process Control. Compatible with actual Windows operating systems. Graphic and intuitive simulation of the process in screen. Sensor and elements Compatible with the industry standards. +Registration and visualization of all process variables in an automatic and simultaneous way. Flexible and open software, developed with actual windows graphic systems, acting simultaneously on all process parameters. Computer Control Software for Temperature Process Control Analog and digital PID control. Menu for PID and set point selection required in the whole work range. Management, processing, comparison and storage of data. Sampling velocity up to 250,000 data per second. UCPCV-T Student calibration system for all sensors involved in the process. It allows the registration of the alarms state and the graphic representation in real time. Comparative analysis of the obtained data, after the process and modification of the conditions during the process. Open software, allowing to the teacher to modify texts, instructions. Teacher's and student's passwords to facilitate the teacher's control on the student, and allowing the access to different work levels. This unit allows the 30 students of the classroom to visualize simultaneously all results and manipulation of the unit, during the process, by using a projector or an electronic whiteboard. UCPCV-C. Set for Flow Process Control: This Set will be supplied and installed in the Base Unit and ready for working. a) Sensor and elements: Turbine type flow sensor, range: 0.25-6.5 l./min. b) Computer Control Software: Computer Control + Data Acquisition + Data Management Software for Flow Process Control. Compatible with actual Windows operating systems. Graphic and intuitive simulation of the process in screen. Compatible with the industry standards. Registration and visualization of all process variables in an automatic and simultaneous way. Sensor and element +Flexible and open software, developed with actual windows graphic systems, acting simultaneously on all process parameters. Analog and digital PID control. Menu for PID and set point selection required in the whole work range. Computer Control Software for Flow Process Control Management, processing, comparison and storage of data. Sampling velocity up to 250,000 data per second. Student calibration system for all sensors involved in the process. It allows the registration of the alarms state and the graphic representation in real time. UCPCV-C Comparative analysis of the obtained data, after the process and modification of the conditions during the process. Open software, allowing to the teacher to modify texts, instructions. Teacher's and student's passwords to facilitate the teacher's control on the student, and allowing the access to different work levels. This unit allows the 30 students of the classroom to visualize simultaneously all results and manipulation of the unit, during the process, by using a projector or an electronic whiteboard. UCPCV-N. Set for Level Process Control: This Set will be supplied and installed in the Base Unit and ready for working. a) Sensor and elements: 0-300mm level sensor (of capacitive immersion, 4-20mA), made with tephlon to avoid any corrosion. b) Computer Control Software: Computer Control + Data Acquisition + Data Management Software for Level Process Control. Compatible with actual Windows operating systems. Graphic and intuitive simulation of the process in screen. Compatible with the industry standards. Sensor and elements Registration and visualization of all process variables in an automatic and simultaneous way. +Flexible and open software, developed with actual windows graphic systems, acting simultaneously on all process parameters. Analog and digital PID control. Menu for PID and set point selection required in the whole work range. Management, processing, comparison and storage of data. mputer Control

Sampling velocity up to 250,000 data per second.

Student calibration system for all sensors involved in the process.

It allows the registration of the alarms state and the graphic representation in real time.

Comparative analysis of the obtained data, after the process and modification of the conditions during the process.

Open software, allowing to the teacher to modify texts, instructions. Teacher's and student's passwords to facilitate the teacher's control on the student, and allowing the access to different work levels.

This unit allows the 30 students of the classroom to visualize simultaneously all results and manipulation of the unit, during the process, by using a projector or an electronic whiteboard.

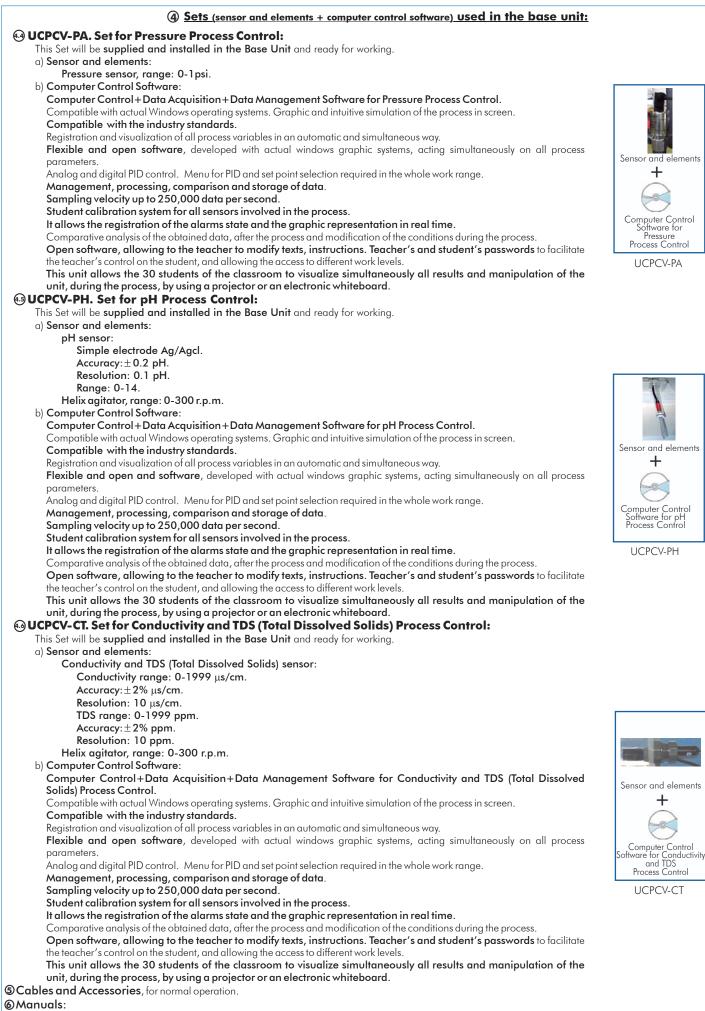


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Process Control

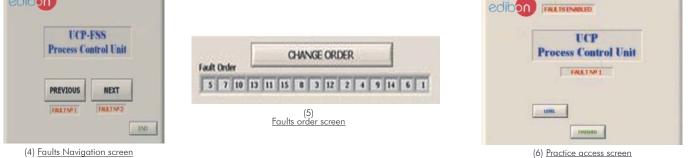
UCPCV-N

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This system is **supplied with 8 manuals for each process control**: Required Services, Assembly and Installation, Interface and Control Software, Starting-up, Safety, Maintenance, Calibration & Practices Manuals.

SPECIFICATIONS Additional and optional items PLC. Industrial Control using PLC (7 and 8): ⑦ PLC-PI. PLC Module: This module is common for all Sets for Process Control type "UCPCV" and can work with one or several sets. Circuit diagram in the front panel. Front panel: adiban Digital inputs(X) and Digital outputs (Y) block: 16 Digital inputs, activated by switches and 16 LEDs for confirmation (red). 14 Digital outputs (through SCSI connector) with 14 LEDs for message (green). Analog inputs block: 16 Analog inputs (-10V. to + 10V.) (through SCSI connector). Analog outputs block: 4 Analog outputs (-10V. to + 10V) (through SCSI connector). Touch screen: High visibility and multiple functions. Display of a highly visible status. Recipe function. Bar graph function. Flow display function. Alarm list. Multi language function. True type fonts. Back panel: Power supply connector. Fuse 2A. RS-232 connector to PC. USB 2.0 connector to PC. Inside: Power supply outputs: 24 Vdc, 12 Vdc, -12 Vdc, 12 Vdc variable. Panasonic PLC: High-speed scan of 0.32 $\mu sec.$ for a basic instruction. Program capacity of 32 Ksteps, with a sufficient comment area. Power supply input (100 to 240 VAC).DC input: 16 (24 VDC).Relay output: 14. High-speed counter. Multi-point PID control. Digital inputs/outputs and analog inputs/outputs Panasonic modules. Communication RS232 wire, to computer (PC). ®UCPCV/PLC-SOF. PLC Control Software: For each particular control process, always included with PLC supply. UCP/FSS. Faults Simulation System: Dn) The "FAULTS" mode consists on causing several faults in the unit normal operation. The FALLISENABLED student must find them and solve them. There are several kinds of faults that can be grouped in three sections: WELLCOME TO Faults affecting the sensors measurement: UCP - An incorrect calibration is applied to them. In this case, the student should proceed to calibrate the affected sensor through the values collection. START - Non-linearity. When we have the measures taken by the sensor, a quadratic or inverse function is applied to them. Thus, the value measured will not be the real one, as in the case above mentioned, but when we calibrate again, the sensor will not operate linearly and we will not be able to calibrate it by lest squares fits. Faults affecting the actuators: (These do not admit solutions. The student must just realise it and notify it.) (2)Faults Configuration Menu screen - Actuators channels interchange at any time during the program execution. This error does not admit any solution. - Response reduction of an actuator. By the reduction of the output voltage in analog outputs, we can get an response with a fraction of what it should be, either with a manual execution or with any control type (ON/OFF, PID...) **ERROR CALIBRATION** Faults in the controls execution: - Inversion of the performance in ON/OFF controls. SH1 T The state of some actuator is inverted, when it should be ON is OFF instead, and vice versa. The student should provide the correct operating logic. Reduction or increase of the calculated total response. Least Squares Fit. We multiply by a factor the total response calculated by the PID, provoking, thus, the other () reduction or increase of the action really applied to the actuator, and the consequent instability of the control. The student should notify it and try to calculate this factor. PTA (10 - The action of some controls is annulled. For example, in a PID control, the derivative action is annulled, becoming thus in a PI control. The student will be able to realise it if for some moments, calculates the PID action and check that the calculations are not correct. In this case, he should say what is the real control applied (PI,PD, etc...). edibon



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PLC-PI

INSTRUCTOR

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UCP-FSS FAULTS CONFIGURATION:

SET ERROR CALIBRATION

CHANGE ORDER

3 7 10 13 11 15 8 3 12 2 4 9 14 6 1

CHANCE STATE

OK

(3)

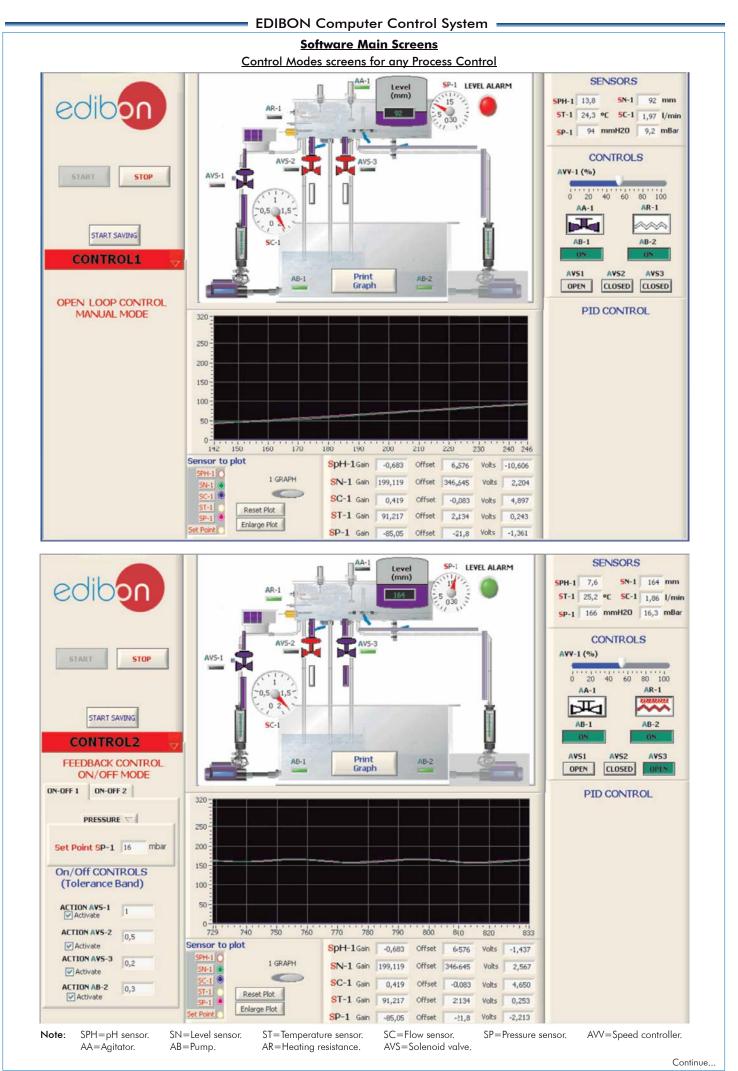
ensors

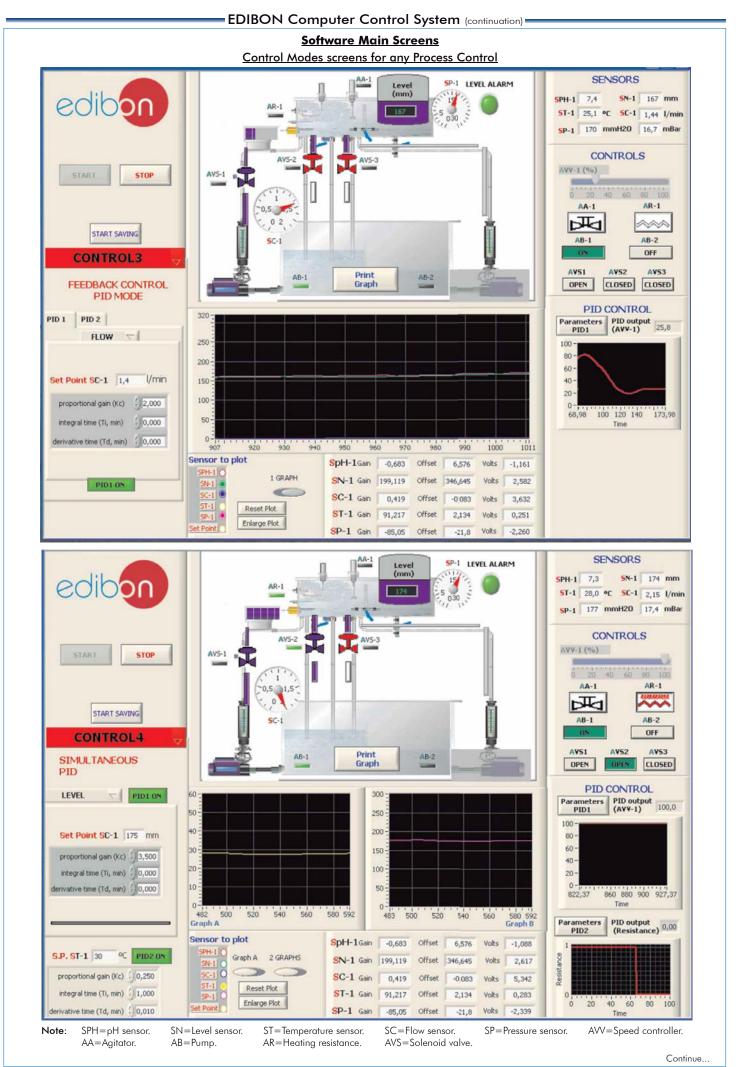
Calibration/ escalibration

screen

(1)

Welcome screen. From the instruction button (with instructor's password) the faults mode is activated.





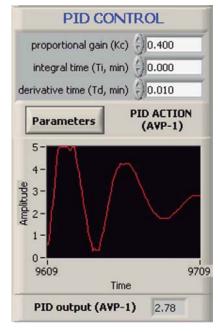
AR-1 Restore Factory Settings ACTUATORS AA-1 AVP-1 SC-1 Analog Input Channel 7 40 50 60 AB-1 Sensor Name SC-1 30 70 -80 20-10-~90 AB-2 Least Squares Fit 0 100 () 0 () 0.210605 Offset () -0.059187 AVS-1 Gain PTA () 10 AVS-2 Calibrated -0.05919 Volts 0 AVS-3 ENTER EXIT

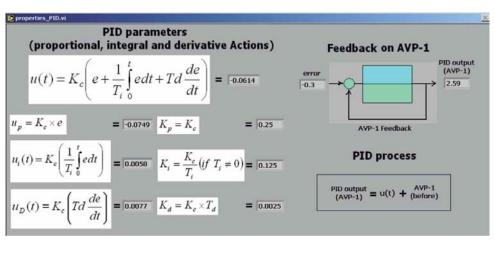
Example of Sensors Calibration screen

Example of On/Off Controls screen

Set Point(Lev	el) 150
On/Off COM (Tolerance	
ACTION AVS-1	2
ACTION AV5-2	2
ACTION AV5-3	10
ACTION AB-2	15

Examples of PID Control screens





Some Practical Possibilities of the System

Temperature Process Control:

- 1.- Temperature control loops(Manual).
- 2.- Temperature control loops(On/Off).
- 3.- Temperature control loops(Proportional).
- 4.- Temperature control loops (Proportional + Integral).
- 5.- Temperature control loops (Proportional + Derivative).
- 6.- Temperature control loops (Proportional + Derivative + Integral).
 7.- Adjustment of the constant of a controller of temperature (Ziegler-Nichols).
- Adjustment of the constant of a controller of temperature (Ziegier-Nichols).
 Adjustment of the constant of a controller of temperature (Reaction Curves).
- Adjustment of the constant of a control
 Temperature sensor calibration.

Flow Process Control:

- 10.- Flow control loops (Manual).
- 11.- Flow control loops (On/Off).
- 12.- Flow control loops (Proportional).
- 13.- Flow control loops (Proportional + Integral).
- 14.- Flow control loops (Proportional + Derivative).
- 15.- Flow control loops (Proportional + Derivative + Integral).
- 16.- Adjustment of the flow controller constants (Ziegler-Nichols).
- 17.- Adjustment of the flow controller constants (Reaction Curves).
- 18.- Flow sensor calibration.

Level Process Control:

- 19.- Level control loops (Manual).
- 20.- Level control loops (On/Off).
- 21.- Level control loops (Proportional).
- 22.- Level control loops (Proportional + Integral).
- 23.- Level control loops (Proportional + Derivative).
- 24.- Level control loops(Proportional + Derivative + Integral).
- 25.- Adjustment of the constants of a flow controller (Ziegler-Nichols).
- 26.- Adjustment of the constants of a flow controller (Reaction Curves).
- 27.- Level sensor calibration.

Pressure Process Control:

- 28.- Pressure control loops (Manual).
- $29.-\ Pressure\ control\ loops (On/Off).$
- 30.- Pressure control loops (Proportional).
- 31.- Pressure control loops (Proportional + Integral).
- 32.- Pressure control loops (Proportional + Derivative).
- 33.- Pressure control loops (Proportional + Derivative + Integral).
- 34.- Adjustment of the constant of a Pressure controller (Ziegler-Nichols).
- 35.- Adjustment of the constant of a Pressure controller (Reaction Curves).
- 36.- Pressure sensor calibration

Practices to be done by PLC (PLC-PI) + PLC Control Software:

(These practices to be able done with each Process Control)

- 1- Control of the unit process through the control interface box without the computer.
- 2.- Visualization of all the sensors values used in the unit process.
- 3.- Calibration of all sensors included in the unit process.
- 4.- Hand on of all the actuators involved in the unit process.
- 5.- Realization of different experiments, in automatic way, without having in front the unit. (This experiment can be decided previously).
- 6.- Simulation of outside actions, in the cases hardware elements do not exist . (Example: test of complementary tanks, complementary industrial environment to the process to be studied, etc).
- 7.- PLC hardware general use and manipulation.
- 8.- PLC process application for unit.
- 9.- PLC structure.

11.- PLC configuration possibilities.

pH).

- 12.- PLC program languages.
- 13.- PLC different programming standard languages.
- 14.- New configuration and development of new process.
- 15.- Hand on an established process.

10.- PLC inputs and outputs configuration.

- 16.- To visualize and see the results and to make comparisons with the unit process.
- 17.- Possibility of creating new process in relation with the unit.

be able to reach is 50%. (Affected sensor: Flow sensor).

Inversion of the performance in ON/OFF controls:

Reduction or increase of the calculated total response:

(Affected sensor: Temperature sensor).

The action of some controls is annulled:

(Proportional-Derivative).

(Proportional-Integral).

Proportional Control.

- 18.- PLC Programming Exercises.
- 19.- Own $\ensuremath{\text{PLC}}$ applications in accordance with teacher and student requirements.

calculated by the PID control. Thus, the maximum real opening that will

thus, on the same way as the others 2 valves (for a good control, it should

operate the other way around to how the others 2 do it). (Affected sensor:

11.- In the ON/OFF control, the actuation of the AVS-1 is inverted, acting,

12.- In the PID, the real action in the resistance is half of the total calculated.

13.- The Integral control does not work. It is reduced to a PD control

14.- The Derivative Control does not work. It is reduced to a PI Control

15.- The Integral and Derivative controls do not work. They are reduced to a

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Practices to be done by Faults Simulation System (UCP/FSS)

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Incorrect Calibration:

- 1.- Load the calibration error of the PH sensor.
- 2.- Load the calibration error of the Level sensor.
- 3.- Load the calibration error of the Flow sensor.
- 4.- Load the calibration error of the Temperature sensor.
- Non Linearity:
- 5.- Non inverse linearity of the pH sensor.
- 6.- Non quadratic linearity of the Level sensor.
- 7.- Non quadratic linearity of the Flow sensor.
- 8.- No inverse linearity of the Temperature sensor.
- Interchange of actuators:
- Interchange the bombs AB-1 and AB-2 between them during the operations of the controls ON/OFF and PID. (Affected sensor: Level sensor)

Reduction of an actuator response:

10.- In the PID, the real response of the proportional valve is half the amount

pH Process Control:

- 37.- pH control loops (Manual).
- 38.- pH control loops(On/Off).
- 39.- pH control loops (Proportional).
- 40.- pH control loops (Proportional + Integral).
- 41.- pH control loops (Proportional + Derivative).
- 42.- pH control loops (Proportional + Derivative + Integral).
- 43.- Adjustment of the constant of a pH controller (Ziegler-Nichols).
- 44.- Adjustment of the constant of a pH controller (Reaction Curves).
- 45.- pH sensor calibration.

Conductivity and TDS (Total Dissolved Solids) Process Control:

- 46.- Conductivity control loops (Manual).
- 47.- Conductivity control loops(On/Off).
- 48.- Conductivity control loops (Proportional).
- 49.- Conductivity control loops (Proportional + Integral).
- 50.- Conductivity control loops (Proportional + Derivative).
- 51.- Conductivity control loops (Proportional + Derivative + Integral).

60.- Adjustment of the constant of a TDS controller (Ziegler-Nichols).

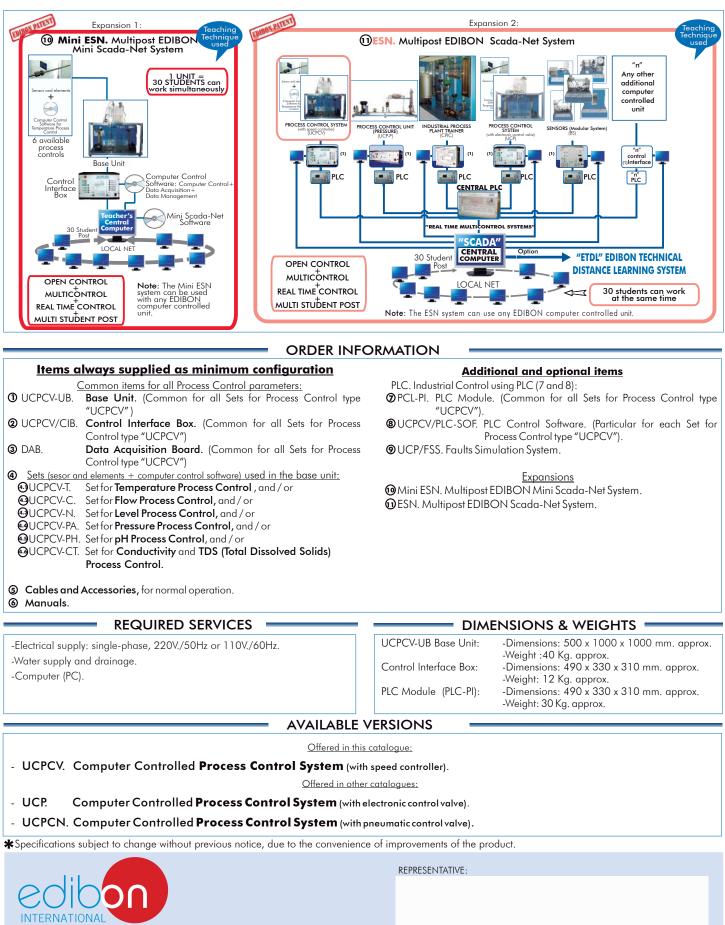
61.- Adjustment of the constant of a TDS controller (Reaction Curves).

- 52.- Adjustment of the constant of a Conductivity controller (Ziegler-Nichols).
- 53.- Adjustment of the constant of a Conductivity controller (Reaction Curves).
- 54.- TDS control loops (Manual).
- 55.- TDS control loops(On/Off).
- 56.- TDS control loops (Proportional).
- 57.- TDS control loops (Proportional + Integral).58.- TDS control loops (Proportional + Derivative).

62.- Conductivity and TDS sensor calibration.

59.- TDS control loops (Proportional + Derivative + Integral).

POSSIBILITIES OF OTHER AVAILABLE EXPANSIONS



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Issue: ED01/13 Date: May/2013